

Newton Polytopes via Witness Sets

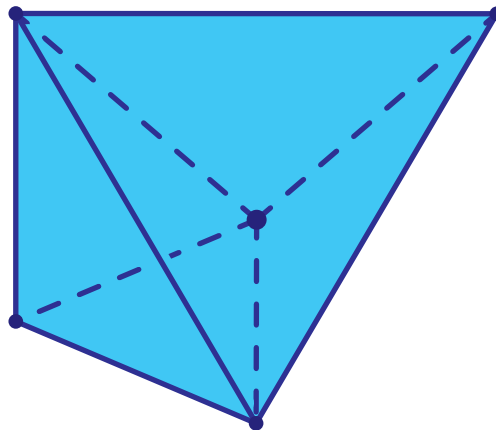
Algebraic and Geometric Methods in
Applied Discrete Mathematics

11 January 2015



Frank Sottile

sottile@math.tamu.edu



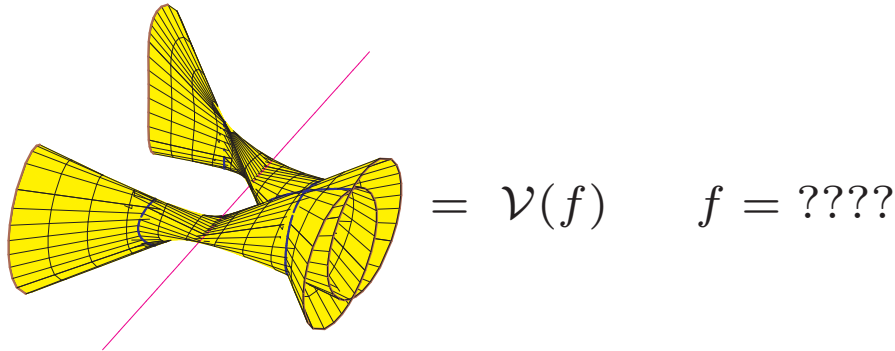
Work with Jon Hauenstein and Taylor Brysiewicz.

Fundamental Problem

By algebraic geometry, an irreducible hypersurface \mathcal{H} in \mathbb{C}^n is defined by the vanishing of a single irreducible polynomial, $f \in \mathbb{C}[x_1, \dots, x_n]$,

$$\mathcal{H} = \mathcal{V}(f) := \{x \in \mathbb{C}^n \mid f(x) = 0\}.$$

The problem I want to consider is: Suppose that we know the hypersurface, but not the polynomial?



We would like to understand the polynomial f defining \mathcal{H} .

What Does *Understand* Mean?

Best: Complete knowledge. There are finite sets $\mathcal{A} \subset \mathbb{Z}^n$ and $\{c_a \mid a \in \mathcal{A}\} \subset \mathbb{C}$ such that

$$f = \sum_{a \in \mathcal{A}} c_a x^a \quad (x^a := x_1^{a_1} \cdots x_n^{a_n})$$

Pretty Good: Knowing the support, \mathcal{A} .

We'll Settle For: Newton Polytope of \mathcal{H} ,

$$N(\mathcal{H}) := \text{convex hull of } \mathcal{A}.$$

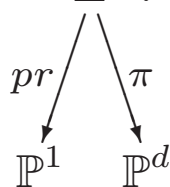
Easier: The degree of \mathcal{H} .

How to Know \mathcal{H} but not f

The hypersurface \mathcal{H} might be the image of a map,

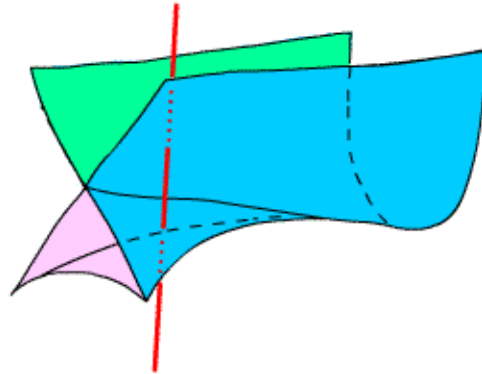
$$\varphi : X \longrightarrow \mathcal{H} \subset \mathbb{C}^n .$$

This is fairly common, for example

$$\Sigma := \{(p, f) \mid p \in \mathbb{P}^1, \deg(f) = d, f_x(p) = f_y(p)\}$$


```
graph TD; Sigma[Σ] -- pr --> P1[ℙ¹]; Sigma -- π --> Pd[ℙᵈ];
```

$pr : \Sigma \rightarrow \mathbb{P}^1$ is a projective bundle,
and $\pi(\Sigma)$ is the classical discriminant
of a d -form.



Example: Lüroth Quartics

Lüroth, 1869: If l_1, \dots, l_5 are equations for lines, then

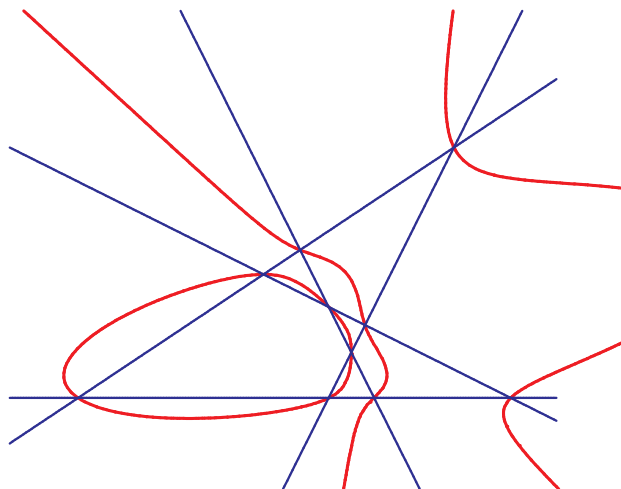
$$q := l_1 l_2 l_3 l_4 l_5 \left(\frac{1}{l_1} + \frac{1}{l_2} + \frac{1}{l_3} + \frac{1}{l_4} + \frac{1}{l_5} \right)$$

defines a quartic that inscribes
the great pentagon,
 $\mathcal{V}(l_1 l_2 l_3 l_4 l_5)$.

This set of quartics is the im-
age of a map $(\mathbb{C}^3)^5 - \rightarrow \mathbb{P}^{14}$
($\mathbb{P}^{14} =$ plane quartics),
and it forms a hypersurface, \mathcal{L} .

Morley, 1919: \mathcal{L} has degree 54.

The defining equation of \mathcal{L} is the *Lüroth invariant*, which could have as
many as $\binom{54+14}{14} = 123234279768160$ monomials.



How to Represent a Polytope?

P = convex hull of a finite subset of \mathbb{R}^n .

$$P = \bigcap_{\omega \text{ in a finite set}} \{x \mid \omega \cdot x \leq b_\omega\},$$

ω in a finite set

the intersection of finitely many half-spaces.

Oracle Representation:

For $\omega \in \mathbb{R}^n$, set $h(\omega) = \max\{\omega \cdot x \mid x \in P\}$.

The face P_ω of P *exposed* by ω is

$$P_\omega := \{x \in P \mid \omega \cdot x = h(\omega)\}$$

The *oracle representation* of P is a function that given $\omega \in \mathbb{R}^n$ returns P_ω , if it is a vertex.

We propose a method, based on **numerical algebraic geometry** to compute an oracle representation of the Newton polytope of a hypersurface.

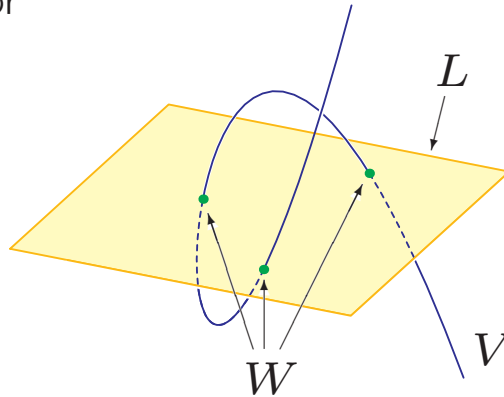
Witness Sets

Numerical Algebraic Geometry uses numerical analysis to represent and manipulate varieties on a computer.

Let $V \subset \mathbb{C}^n$ be a variety of codimension k , given as a component of $F(x) = 0$. A *witness set* for

V is a pair (W, L) , where

- L is a general affine plane of dimension k , and
- $W = V \cap L$.



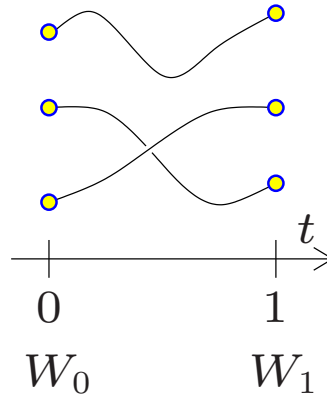
L is either parameterized, or cut out by $n - k$ affine forms, and W consists of numerical approximations to $V \cap L$.

Continuation

In numerical algebraic geometry, the basic operation is **continuation**, which traces points along implicitly-defined paths.

Suppose that $L(t)$ for $t \in \mathbb{C}$ is a family of k -planes, and we have a witness set $(W_1, L(1))$ for V .

We numerically continue these points in $V \cap L(t)$ from $t = 1$ to $t = 0$ to get another witness set $(W_0, L(0))$ for V .



This allows us to sample points from V .

Witness Sets of Projections

Our hypersurfaces come as the image under a projection.

Suppose that $X \subset \mathbb{C}^n \oplus \mathbb{C}^m$ and $\mathcal{H} = \pi(X) \subset \mathbb{C}^n$ is a hypersurface.

Hauenstein, Sommese, Wampler: Given a witness set $(X \cap L, L)$ for X , compute a witness set $(\mathcal{H} \cap \ell, \ell)$ for \mathcal{H} :

— Choose a general lines $\ell \subset \mathbb{C}^n$

— Move L to a non-general plane Λ with $\pi(\Lambda) = \ell$.

Set $W' := X \cap \Lambda$. Then $(\pi(W'), \ell)$ is a witness set for \mathcal{H} .

Delicate: Λ is not in general position.

Witness set of a Hypersurface

Suppose $f = \sum_{a \in \mathcal{A}} c_a x^a$ is a polynomial, $\mathcal{H} := \mathcal{V}(f)$, and $P = \text{conv}(\mathcal{A})$.

Let $p, q \in \mathbb{C}^n$ be general, and define

$$\ell_{p,q}(s) = \ell(s) := \{sp - q \mid s \in \mathbb{C}\}.$$

Then $f(\ell(s)) = 0$ defines the witness set $\mathcal{H} \cap \ell$.

Thus a witness set gives roots of $f(\ell(s))$.

For $\omega \in \mathbb{R}^n$ and $t > 0$, set $t^\omega := (t^{\omega_1}, \dots, t^{\omega_n})$. Then,

$$\begin{aligned} f(t^\omega \cdot \ell(s)) &= \sum_{a \in \mathcal{A}} c_a (sp_1 - q_1)^{a_1} \cdots (sp_n - q_n)^{a_n} t^{\omega \cdot a} \\ &\stackrel{!}{=} t^{h(\omega)} \left(\sum_{\mathcal{A} \cap P_\omega} c_a (sp - q)^a + \sum_{\mathcal{A} \setminus P_\omega} c_a (sp - q)^a t^{\omega \cdot a - h(\omega)} \right) \end{aligned}$$

$\Rightarrow \exists d_\omega > 0$ such that $\omega \cdot a - h(\omega) < -d_\omega$ for $a \in \mathcal{A} \setminus P_\omega$.

Main Lemma

$$f(t^\omega \cdot \ell(s)) = t^{h(\omega)} \left(\sum_{A \cap P_\omega} c_a(sp-q)^a + \sum_{A \setminus P_\omega} c_a(sp-q)^a t^{\omega \cdot a - h(\omega)} \right)$$

Set f_ω to be the sum of terms in f from P_ω

Lemma. *In the limit as $t \rightarrow \infty$, $t^{-h(\omega)} f(t^\omega \cdot \ell(s)) \rightarrow f_\omega(\ell(s))$. $\deg(f) - \deg(f_\omega)$ zeroes will diverge to ∞ , while the remaining $\deg(f_\omega)$ remaining bounded.*

If P_ω is a vertex, say a (which holds when ω is generic), then

$$f_\omega(\ell(s)) = c_a(sp_1 - q_1)^{a_1} \cdots (sp_n - q_n)^{a_n}.$$

Thus a_i zeroes of $f(t^\omega \cdot \ell(s))$ coalesce to q_i/p_i as $t \rightarrow \infty$.

Our paper describes how to turn this idea into an algorithm.

Lüroth quartics, again

We created a test implementation and used it to compute a few vertices of the *Lüroth polytope* (Newton polytope of the Lüroth hypersurface).

Ciani quartics: The Lüroth quartics whose monomials are squares,

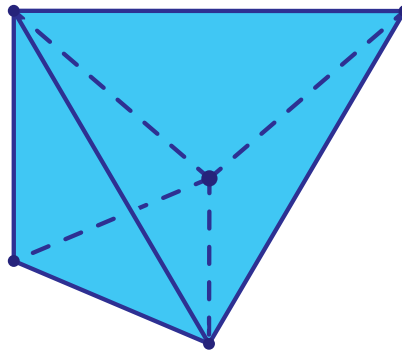
$$\alpha x^4 + \beta y^4 + \gamma z^4 + 2(\delta x^2 y^2 + \rho x^2 z^2 + \sigma y^2 z^2),$$

form a face of the Lüroth polytope, which we computed.

It is $14 \triangle + \alpha^4 \beta^4 \gamma^4$,

where \triangle is equivalent to the bipyramid,

$$\text{conv} \begin{pmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{pmatrix} =$$



Ciani Face of Lüroth Invariant

We used a numerical factorization algorithm and an LLL-based interpolation method to compute the Lüroth invariant, restricted to this face of Ciani quartics, $f(\mathcal{L})_\omega$.

$$f(\mathcal{L})_\omega = \alpha^4 \beta^4 \gamma^4 f_1^4 f_2^2 f_3^2 f_4^2 \cdot f_5,$$

where f_1, \dots, f_5 have integer coefficients, between 1 and $2401 = 7^4$.

f_1, f_2, f_3, f_4 have the same Newton polytope, , but

f_5 has Newton polytope 4 .

Subsequently, Basson, Lercier, Ritzenthaler, and Sijsling found an expression for the Lüroth invariant in terms of the fundamental and secondary invariants of $GL(3)$ acting on quartics.

f_5

$$\begin{aligned} & 2401\alpha^4\beta^4\gamma^4 - 196\alpha^4\beta^3\gamma^3\sigma^2 + 102\alpha^4\beta^2\gamma^2\sigma^4 - 4\alpha^4\beta\gamma\sigma^6 + \alpha^4\sigma^8 - 196\alpha^3\beta^4\gamma^3\rho^2 \\ & - 196\alpha^3\beta^3\gamma^4\delta^2 + 840\alpha^3\beta^3\gamma^3\delta\rho\sigma - 820\alpha^3\beta^3\gamma^2\rho^2\sigma^2 - 820\alpha^3\beta^2\gamma^3\delta^2\sigma^2 + 232\alpha^3\beta^2\gamma^2\delta\rho\sigma^3 \\ & - 12\alpha^3\beta^2\gamma\rho^2\sigma^4 - 12\alpha^3\beta\gamma^2\delta^2\sigma^4 - 40\alpha^3\beta\gamma\delta\rho\sigma^5 + 4\alpha^3\beta\rho^2\sigma^6 + 4\alpha^3\gamma\delta^2\sigma^6 - 8\alpha^3\delta\rho\sigma^7 \\ & + 102\alpha^2\beta^4\gamma^2\rho^4 - 820\alpha^2\beta^3\gamma^3\delta^2\rho^2 + 232\alpha^2\beta^3\gamma^2\delta\rho^3\sigma - 12\alpha^2\beta^3\gamma\rho^4\sigma^2 + 102\alpha^2\beta^2\gamma^4\delta^4 \\ & + 232\alpha^2\beta^2\gamma^3\delta^3\rho\sigma + 128\alpha^2\beta^2\gamma^2\delta^2\rho^2\sigma^2 - 80\alpha^2\beta^2\gamma\delta\rho^3\sigma^3 + 6\alpha^2\beta^2\rho^4\sigma^4 - 12\alpha^2\beta\gamma^3\delta^4\sigma^2 \\ & - 80\alpha^2\beta\gamma^2\delta^3\rho\sigma^3 + 220\alpha^2\beta\gamma\delta^2\rho^2\sigma^4 - 24\alpha^2\beta\delta\rho^3\sigma^5 + 6\alpha^2\gamma^2\delta^4\sigma^4 - 24\alpha^2\gamma\delta^3\rho\sigma^5 \\ & + 24\alpha^2\delta^2\rho^2\sigma^6 - 4\alpha\beta^4\gamma\rho^6 - 12\alpha\beta^3\gamma^2\delta^2\rho^4 - 40\alpha\beta^3\gamma\delta\rho^5\sigma + 4\alpha\beta^3\rho^6\sigma^2 - 12\alpha\beta^2\gamma^3\delta^4\rho^2 \\ & - 80\alpha\beta^2\gamma^2\delta^3\rho^3\sigma + 220\alpha\beta^2\gamma\delta^2\rho^4\sigma^2 - 24\alpha\beta^2\delta\rho^5\sigma^3 - 4\alpha\beta\gamma^4\delta^6 - 40\alpha\beta\gamma^3\delta^5\rho\sigma \\ & + 220\alpha\beta\gamma^2\delta^4\rho^2\sigma^2 - 272\alpha\beta\gamma\delta^3\rho^3\sigma^3 + 48\alpha\beta\delta^2\rho^4\sigma^4 + 4\alpha\gamma^3\delta^6\sigma^2 - 24\alpha\gamma^2\delta^5\rho\sigma^3 \\ & + 48\alpha\gamma\delta^4\rho^2\sigma^4 - 32\alpha\delta^3\rho^3\sigma^5 + \beta^4\rho^8 + 4\beta^3\gamma\delta^2\rho^6 - 8\beta^3\delta\rho^7\sigma + 6\beta^2\gamma^2\delta^4\rho^4 - 24\beta^2\gamma\delta^3\rho^5\sigma \\ & + 24\beta^2\delta^2\rho^6\sigma^2 + 4\beta\gamma^3\delta^6\rho^2 - 24\beta\gamma^2\delta^5\rho^3\sigma + 48\beta\gamma\delta^4\rho^4\sigma^2 - 32\beta\delta^3\rho^5\sigma^3 + \gamma^4\delta^8 - 8\gamma^3\delta^7\rho\sigma \\ & + 24\gamma^2\delta^6\rho^2\sigma^2 - 32\gamma\delta^5\rho^3\sigma^3 + 16\delta^4\rho^4\sigma^4. \end{aligned}$$

The Future

This approach to finding Newton polytopes of hypersurface, and possibly using that information with interpolation to find a defining polynomial appears feasible, and would have many applications, were a proper implementation made.

This is a current project of Taylor Brysiewicz, a graduate student at TAMU.

REFERENCES

- [1] R. Basson, R. Lercier, C. Ritzenthaler, and J. Sijssling, An explicit expression of the Lüroth invariant, ISSAC 13, ACM, New York, 2013, pp. 31–36.
- [2] J. Hauenstein and F. Sottile, Newton Polytopes and Witness Sets,] Mathematics in Computer Science, 8 (2014), pp. 235–251.